

RFNoC 4 Migration Guide

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The UHD 4.0 release includes a major upgrade to the RFNoC framework called RFNoC 4. This article is a guide to aid users in migrating their existing RFNoC blocks from RFNoC 3 to RFNoC 4. The RFNoC Block Development Environment section provides guidance on how to setup an environment for developing out-of-tree RFNoC blocks in RFNoC 4. The UHD, FPGA, GNU Radio Migration sections provide general information on topics that most users will encounter when migrating their blocks. Finally, an equivalent RFNoC 3 and RFNoC 4 implementation of a digital gain RFNoC Block has been provided as a reference.

```
sudo apt-get install autoconf automake build-essential ccache cmake cpufrequtils doxygen ethtool \
g++ git inetutils-tools libboost-all-dev libncurses5 libncurses5-dev libusb-1.0-0 libusb-1.0-0-dev \
libusb-dev python3-dev python3-mako python3-numpy python3-requests python3-scipy python3-setuptools \
python3-ruamel.yaml libtinfo5 libncurses5
```

Please reference to Xilinx (xilinx.com) for installation instructions.

Note: The dependencies step above included installing libtinfo5 libncurses5, which is a workaround for getting Vivado 2019.1 to run on Ubuntu 20.04

```
git clone --branch UHD-4.1 https://github.com/ettusresearch/uhd.git uhd
mkdir uhd/host/build; cd uhd/host/build
cmake ..
make
sudo make install
```

Note: If your design does not use GNU Radio, then installing GNU Radio and gr-ettus is not required

```
git clone --branch maint-3.8 --recursive https://github.com/gnuradio/gnuradio.git gnuradio
mkdir gnuradio/build; cd gnuradio/build;
cmake ..
make
sudo make install
```

Please refer to the [GNU Radio Build Instructions](#) for dependencies and a more detailed description.

```
git clone --branch maint-3.8-uhd4.0 https://github.com/ettusresearch/gr-ettus.git gr-ettus
mkdir gr-ettus/build; cd gr-ettus/build;
cmake -DENABLE_QT=True ..
make
sudo make install
```

Two options exist for developing RFNoC blocks depending on whether the your RFNoC block integrates with GNU Radio in an out-of-tree module or if it only uses UHD's C++ API in a standalone application. The sections below outline how to setup the development environment for each scenario.

The tool rfnocmodtool automates the process of creating GNU Radio out-of-tree (OOT) modules that also have support for RFNoC blocks. This tool is part of gr-ettus and it has been ported to RFNoC 4.

Due to changes in almost every source file, it is recommended to use rfnocmodtool to generate a new RFNoC block from scratch and then update the generated ?skeleton? files.

The following steps show how to create an OOT module called *example* and RFNoC block called *gain* using rfnocmodtool. The naming is only for example purposes.

```
rfnocmodtool newmod
Name of the new module: example

cd rfnoc-tutorial
rfnocmodtool add
Enter name of block/code (without module name prefix): gain
Enter valid argument list, including default arguments: (leave blank)
Add Python QA code? [y/N] N
Add C++ QA code? [y/N] N
Block NoC ID (Hexadecimal): (Enter Noc ID of your block)
Skip Block Controllers Generation? [UHD block ctrl files] [y/N] N
Skip Block interface files Generation? [GRC block ctrl files] [y/N] N
```

Note: Noc IDs have been reduced from 64-bits in RFNoC 3 to 32-bits in RFNoC 4

The following are the relevant files that need to be updated when migrating your RFNoC Block.

```
rfnoc-example/
  grc/
    example_gain.block.yml          ? RFNoC Block GNU Radio Companion YAML file
  examples/
    gain.grc                        ? Example flowgraph using gain RFNoC Block
  include/tutorial/
    gain.h                          ? GNU Radio block C++ header
    gain_block_ctrl.hpp            ? RFNoC Block Controller C++ header
  lib/
    gain_impl.cc                   ? GNU Radio block C++ source
    gain_impl.h                   ? GNU Radio block C++ header
    gain_block_ctrl_impl.cpp       ? RFNoC Block Controller C++ source
  rfnoc/blocks/
    gain.yml                       ? RFNoC Block Description YAML file
  rfnoc/fpga/rfnoc_block_gain
    noc_shell_gain.v              ? RFNoC Block Noc Shell Verilog Source
    rfnoc_block_gain.v            ? RFNoC Block Verilog Source
    rfnoc_block_gain_tb.v         ? RFNoC Block Testbench
  rfnoc/icores
    gain_x310_rfnoc_image_core.yml ? Image Core YAML file with gain block

cd rfnoc-tutorial
mkdir build; cd build
cmake -DUHD_FPGA_DIR=(path to uhd/fpga directory) ..
make
sudo make install
```

CMake automatically creates makefile targets to run the generated testbench code for each added RFNoC block. For example, here is how to run the gain block testbench:

```
cd rfnoc-tutorial/build
make rfnoc_block_gain_tb
```

CMake automatically creates makefile targets to build FPGA images using the generated image core yaml files found in rfnoc/icore. Every RFNoC block created by rfnocmodtool automatically has an image core yaml file generated in that directory. For example, here is how to build an FPGA image using the image core yaml file generated for the gain block:

```
cd rfnoc-tutorial/build
make gain_x310_rfnoc_image_core
```

For applications that only use the UHD API, an example out-of-tree (UHD source tree) RFNoC block exists called rfnoc-example. It is located in the UHD source at uhd/host/examples/rfnoc-example. This directory can be copied outside of the UHD source tree and used as a starting point to migrate your RFNoC block.

The following are the relevant files that need to be updated when migrating your RFNoC Block.

```
rfnoc-example/
  apps/
    init_gain_block.cpp            ? Example C++ application testing gain block
  blocks/
    gain.yml                      ? RFNoC Block Description YAML file
  fpga/rfnoc_block_gain
    noc_shell_gain.v              ? RFNoC Block Noc Shell Verilog Source
    rfnoc_block_gain.v            ? RFNoC Block Verilog Source
    rfnoc_block_gain_tb.v         ? RFNoC Block Testbench
  icores/
    x310_rfnoc_image_core.yml     ? Example Image Core YAML file
  include/rfnoc/example
    gain_block_control.hpp        ? RFNoC Block Controller C++ header
  lib/
    gain_block_control.cpp        ? RFNoC Block Controller C++ source

cd rfnoc-example
mkdir build; cd build
cmake ..
make
sudo make install
```

CMake automatically creates makefile targets to run RFNoC Block testbench simulations. For every RFNoC block subdirectory listed in the CMakeLists.txt file in the rfnoc-example/fpga directory, a target with the RFNoC block name appended with ?_tb? is added as a makefile target. For example, here is how to run the gain RFNoC block testbench:

```
cd rfnoc-example/build
make rfnoc_block_gain_tb
```

CMake automatically creates makefile targets to build a FPGA image for each image core yaml file listed in the CMakeLists.txt file in the rfnoc-example/icore directory. Each image core yaml file must be listed in the CMakeLists.txt. For example, here is how to build an FPGA image using the image core yaml file generated for the gain block:

```
cd rfnoc-tutorial/build
make gain_x310_rfnoc_image_core
```

This ZIP archive, [File:migration example.zip](#), contains equivalent RFNoC 3 and RFNoC 4 versions of a digital gain RFNoC Block. The following sections will refer to files in this archive to show how the file structure changes when migrating from RFNoC 3 to RFNoC 4.

Migration reference files for this section from the Gain RFNoC Block example:

Description	RFNoC 3 Files	RFNoC 4 Files
Block Description	rfnoc/blocks/gain.xml	lib/gain_block_ctrl_impl.cpp include/example/gain_block_ctrl.hpp
Block Controller	rfnoc/blocks/gain.yml	lib/gain_block_ctrl_impl.cpp include/example/gain_block_ctrl.hpp

Note: Files are relative to the rfnoc-example directory in the respective rfnoc3 and rfnoc4 directories

RFNoC 3 used Noc Script XML, a domain specific language, to describe the configuration of a RFNoC block: the Noc ID, register names and addresses, args for writing to the registers, and the input/output ports.

RFNoC 4 replaces the Noc Script XML file with an easier to read and edit Block Description YAML file format. From a high level, the Block Description YAML file serves a similar function as the Noc Script XML file, with some similarities and key differences outlined in table below:

Item	Noc Script XML	Block Descript YAML	RFNoC 4 Notes
Block Name	<name>gain</name>	module_name: gain	
Noc ID	<id>B160000000000000</id>	noc_id: 0xB16	Noc ID are limited to 32-bits
Registers	<registers> <setreg> <name>GAIN</name> <address>128</address> </setreg> </registers>	N/A	Registers must be defined in the Block Controller
Arguments	<args> <arg> <name>gain</name> <type>int</type> ... </arg> </args>	N/A	Args are implemented with properties in the Block Controller
Data Ports	<ports> <sink> <name>in</name> </sink> <name>out</name> </ports>	data: fpga_iface: axis_pyld_ctxt clk_domain: rfnoc_chdr inputs: in: ... outputs: out: ... control: sw_iface: nocscript fpga_iface: ctrlport interface_direction: slave ... clocks: - name: rfnoc_chdr freq: "[]" - name: rfnoc_ctrl freq: "[]"	
Control Ports	N/A		
Clocking	N/A		

Note: For a more detailed description of the RFNoC 4 Block Description YAML syntax and the various options, see the [RFNoC Specification](#).

Much of the user facing RFNoC software API has not changed or remains very similar between RFNoC 3 and RFNoC 4. The table below outlines some of the notable differences:

RFNoC 3	RFNoC 4	RFNoC 4 Notes
usrp = uhd::device3::make(...)	graph = uhd::rfnoc::rfnoc_graph::make()	No longer need to create a device3 object
usrp->get_block_ctrl(...)	graph->get_block(...)	Rename
N/A	graph->enumerate_static_connections()	Used to check static connections, for example the DDC and DUC blocks are usually statically connected to the radio block
usrp->get_tx_streamer(...)	graph->create_tx_streamer(...)	Rename
usrp->get_rx_streamer(...)	graph->create_rx_streamer(...)	Rename
N/A	graph->commit()	Commit graph and run initial checks
sr_write(...)	regs().poke32(...)	Address increments by 4
sr_read32(...)	regs().peek32(...)	Address increments by 4
sr_read64(...)	regs().poke64(...)	Address increments by 8
set_arg(...)	set_property(...)	Block args replaced with block properties concept
get_arg(...)	get_property(...)	Block args replaced with block properties concept

In RFNoC 3, RFNoC blocks can have arguments (also known as args) that are used to write user registers. This is implemented in the Noc Script XML in the <args> section.

RFNoC 4 expands and generalizes this concept with block properties: a high-level representation of the state of the block. Zero or more properties can be defined by the user in their RFNoC Block's Block Controller C++ class. When read or written to, they can trigger a callback to a user defined resolver function. The [RFNoC Specification](#) provides more details on properties in the [Block Properties](#) section.

The following shows an example of how to migrate a RFNoC 3 Noc Script XML [?arg?](#) based register write to a RFNoC 4 property based implementation in the Block Controller:

```
<registers>
  <setreg>
    <name>GAIN</name>
    <address>128</address>
  </setreg>
</registers>

<args>
  <arg>
    <name>gain</name>
    <type>int</type>
    <value>1</value>
    <check>GE($gain, 0) AND LE($gain, 32767)</check>
    <check_message>Gain must be in the range [0, 32767]</check_message>
    <action>SR_WRITE("GAIN", $gain)</action>
  </arg>
</args>

// <registers>
//   <setreg>
//     <name>GAIN</name>
//     <address>128</address>
//   </setreg>
// </registers>
// Note: In RFNoC 4, register addresses can start at address 0 instead of address 128 as in RFNoC 3.
const uint32_t gain_block_ctrl::REG_GAIN_ADDR = 0;
const uint32_t gain_block_ctrl::REG_GAIN_DEFAULT = 1;

class gain_block_ctrl_impl : public gain_block_ctrl
{
public:
  RFNOC_BLOCK_CONSTRUCTOR(gain_block_ctrl)
  {
    _register_props();
  }
private:
  void _register_props()
  {
    register_property(&_user_reg, [this]() {
      int user_reg = this->_user_reg.get();
      // <check>GE($gain, 0) AND LE($gain, 32767)</check>
      // <check_message>Gain must be in the range [0, 32767]</check_message>
      if (user_reg < 0 || user_reg > 32767) {
        throw uhd::value_error("Size value must be in [0, 32767]");
      }
      // <action>SR_WRITE("GAIN", $gain)</action>
      this->regs().poke32(REG_USER_ADDR, user_reg);
    });
  }
};

// <name>gain</name>
// <type>int</type>
// <value>1</value>
property_t<int> _user_reg{"gain", REG_USER_DEFAULT, {res_source_info::USER}};
```

As the above shows, writing to a register can be replicated with a property and a resolver function. Of course, the resolver function can also be made much more sophisticated. For additional examples, see the in-tree block controllers in [uhd/host/lib/rfnoc](#).

Migration reference files for this section from the Gain RFNoC Block example:

Description	RFNoC 3 Files	RFNoC 4 Files
Block Verilog Code	rfnoc/fpga-src/noc_block_gain.v	rfnoc/fpga/rfnoc_block_gain/rfnoc_block_gain.v
Block Noc Shell	N/A	rfnoc/fpga/rfnoc_block_gain/noc_shell_gain.v
Block Testbench	rfnoc/testbench/noc_block_gain/noc_block_gain_tb.sv	rfnoc/fpga/rfnoc_block_gain/rfnoc_block_gain_tb.sv
Image Core	N/A	rfnoc/icores/gain_x310_rfnoc_image_core.yml

Note: Files are relative to the rfnoc-example directory in the respective rfnoc3 and rfnoc4 directories

RFNoC 4 replaces the highly parameterized RFNoC 3 Noc Shell with a per-block customized Noc Shell generated from the block's Block Description YAML file. The Noc Shell generated via rfnocmodtool or the existing one in rfnoc-example is acceptable for most blocks that require one input and output data port.

Some blocks may need multiple data ports or other modifications. This requires editing the Block Description YAML file and then using the Python script rfnoc_create_verilog.py (found in uhd/host/utis/rfnoc_blocktool) to generate a new Noc Shell instance.

The argument [?-c?](#) is used to provide the YAML file location. [?-d?](#) provides the output destination directory.

Note: It is suggested to not set the destination directory to your existing RFNoC block code, as the script will automatically overwrite the existing code!

Example usage:

```
rfnoc_create_verilog.py -c ./rfnoc-example/rfnoc/blocks/gain.yml -d ./output/
```

In the generated Noc Shell Verilog code, a block's Noc ID can be changed by updating the `NOC_ID` parameter on the `backend_iface` module. Make sure this matches the Noc ID in both the Block Description YAML file and Block Controller C++ code.

The RFNoC 3 version of Noc Shell outputs / accepts CHDR data packets consisting of a header, optional timestamp, and payload on a 64-bit AXI stream bus. Most designs then used a module called AXI Wrapper to handle the conversion between CHDR data packets and sample streams on a 32-bit AXI stream bus. AXI Wrapper also supported `SIMPLE_MODE` which for some use cases could transparently handle the header portion of the CHDR data packet. Otherwise, the user would need to set the header via `m_axis_data_tuser`.

In RFNoC 4, Noc Shell has absorbed AXI Wrapper's functionality. Noc Shell outputs two AXI stream buses per input / output port: a payload and context bus. The payload bus is in most cases identical to AXI Wrapper's output: a 32-bit stream of samples on an AXI Stream bus with packets delimited by `tlast`. The context AXI stream bus carries the header, optional timestamp, and optional metadata. If your block used AXI Wrapper's `SIMPLE_MODE`, then you can loop the context bus back into Noc Shell. If not, you will need to modify the context bus data. Refer to the [RFNoC Specification](#) for the format and timing diagram of the context bus.

Important Note: If your block used the AXI Rate Change module, Noc Shell has another data port mode to support this use case called **`axis_data`** that can be set in the Block Descriptor YAML file (see the `ipga_iface` entry). This mode causes the Noc Shell data ports to look more like AXI Wrapper's and therefore makes them compatible with AXI Rate Change. See the `DDC`, `DUC`, or `Keep One in N RFNoC Blocks` for an example.

CtrlPort replaces the Settings Bus in RFNoC 4. The CtrlPort bus is similar to the Settings Bus with a few key differences. The table below compares the signaling between the two bus formats and provides notes on any differences. Timing diagrams and additional information on the CtrlPort bus are also available in the [RFNoC Specification](#).

Settings Bus (RFNoC 3)	CtrlPort (RFNoC 4)	RFNoC 4 Notes
<code>set_stb</code>	<code>ctrlport_reg_wr</code>	Write strobe
<code>set_addr</code>	<code>ctrlport_req_addr</code>	20-bits instead of 8-bits, increments by 4 instead of by 1, no reserved addresses (versus addresses 0-127 for Settings Bus)
<code>set_data</code>	<code>ctrlport_req_data</code>	Write data
N/A	<code>ctrlport_req_rd</code>	Read strobe equivalent of <code>ctrlport_req_wr</code>
<code>rb_addr</code>	N/A	CtrlPort uses <code>ctrlport_req_addr</code> for both read and write addresses
<code>rb_data</code>	<code>ctrlport_resp_data</code>	Read data, 32-bits instead of 64-bits
<code>rb_stb</code>	N/A	CtrlPort requires ack strobe for reads and writes

One additional difference when using CtrlPort is that there is not an equivalent Settings Register module. The bus is simple enough to setup a clocked process to handle reading from and writing to registers. See the Verilog example below:

```
// Note: Register addresses increment by 4
localparam REG_USER_ADDR = 0; // Address for example user register
localparam REG_USER_DEFAULT = 0; // Default value for user register

reg [31:0] reg_user = REG_USER_DEFAULT;

always @(posedge ctrlport_clk) begin
    if (ctrlport_rst) begin
        reg_user = REG_USER_DEFAULT;
    end else begin
        // Default assignment
        m_ctrlport_resp_ack <= 0;

        // Read user register
        if (m_ctrlport_req_rd) begin // Read request
            case (m_ctrlport_req_addr)
                REG_USER_ADDR: begin
                    m_ctrlport_resp_ack <= 1;
                    m_ctrlport_resp_data <= reg_user;
                end
            endcase
        end

        // Write user register
        if (m_ctrlport_req_wr) begin // Write request
            case (m_ctrlport_req_addr)
                REG_USER_ADDR: begin
                    m_ctrlport_resp_ack <= 1;
                    reg_user <= m_ctrlport_req_data[31:0];
                end
            endcase
        end
    end
end
```

Important Note: For blocks that make heavy use of the Settings Bus and/or Settings Registers, there is a CtrlPort to Settings Bus bridge available called **`ctrlport_to_settings_bus`**. See the `Keep One In N RFNoC Block` for example code on how to interface with it.

While RFNoC 4 does overhaul the RFNoC 3 testbench infrastructure API, most of the high level concepts remain the same. The table below outlines some of the commonly used RFNoC 3 functions / code and the RFNoC 4 equivalent.

Operation	RFNoC 3	RFNoC 4
Setup RFNoC	<code>`RFNOC_SIM_INIT(...)</code> <code>`RFNOC_ADD_BLOCK(...)</code> <code>`RFNOC_CONNECT(...)</code>	<code>RfnocBlockCtrlBfm #(...) blk_ctrl = new(...);</code> <code>blk_ctrl.connect_master_data_port(...)</code> <code>blk_ctrl.connect_slave_data_port(...)</code> <i>Note: Instantiate one Block Controller BFM per RFNoC Block</i>
Setup Test Cases	<code>`TEST_CASE_START(...)</code> <code>`TEST_CASE_DONE(...)</code>	<code>test.start_test(...)</code> <code>test.end_test()</code>
Register Read	<code>tb_streamer.read_reg(...)</code>	<code>blk_ctrl.reg_read(...)</code>
Register Write	<code>tb_streamer.write_reg(...)</code>	<code>blk_ctrl.reg_write(...)</code>
Send Data / Samples	<code>tb_streamer.send(...)</code>	<code>blk_ctrl.send_items(...)</code>
Receive Data / Samples	<code>tb_streamer.recv(...)</code>	<code>blk_ctrl.recv_items(...)</code>

RFNoC 4 replaces `uhd_image_builder`, the RFNoC 3 FPGA image building tool, with a new tool called `rfnoc_image_builder`. This tool produces a FPGA bitstream based on an Image Core YAML file that describes the device configuration (e.g. X310 with dual 10GigE) and included RFNoC blocks along with their connections (both static and dynamic), clocking, and I/O.

Both `rfnocmodtool` and the UHD in-tree example called `rfnoc-example` automatically setup make targets to handle running `rfnoc_image_builder`. If you want to use `rfnoc_image_builder` directly, more details can be found in the [Getting Started with RFNoC in UHD 4.0](#).

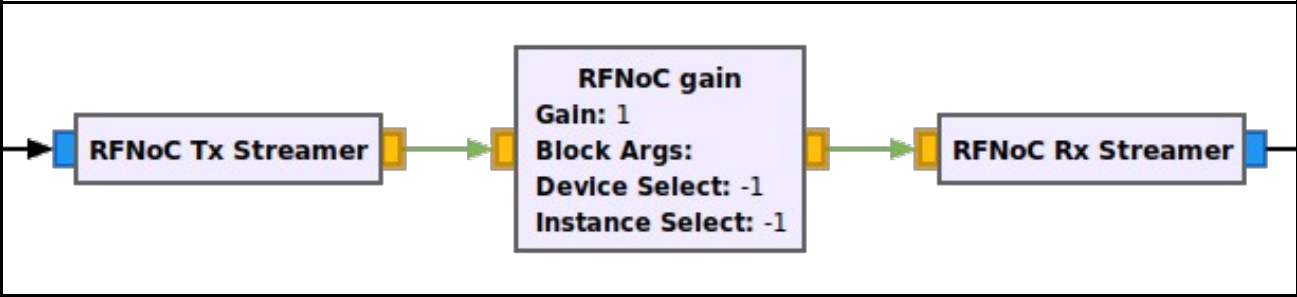
RFNoC 4 supports GNU Radio 3.8 only. Most of your RFNoC Block's GNU Radio related changes will be due to API differences between GNU Radio 3.7 to 3.8. These changes are outside of the scope of this article. Instead, refer to [GNU Radio 3.8 Migration Guide](#) and [GNU Radio Companion YAML](#) sites for more information.

Migration reference files for this section from the Gain RFNoC Block example:

Description	RFNoC 3 Files	RFNoC 4 Files
GNU Radio Block	<code>lib/gain_impl.cc</code>	<code>lib/gain_impl.cc</code>
	<code>lib/gain_impl.h</code>	<code>lib/gain_impl.h</code>
	<code>include/example/gain.h</code>	<code>include/example/gain.h</code>
GRC Block Description	<code>grc/gain.xml</code>	<code>grc/gain.yml</code>
Example GRC Flowgraph	<code>examples/gain.grc</code>	<code>examples/gain.grc</code>

Note: Files are relative to the `rfnoc-example` directory in the respective `rfnoc3` and `rfnoc4` directories

When transition between a RFNoC block and a GNU Radio block or vice versa, you must insert either a RX stream or TX streamer block respectively. This differs from RFNoC 3, where a RFNoC block could be directly connected to a GNU Radio block.



The base class for RFNoC Block's in GNU Radio have a set of functions that provide a shortcut to getting and setting properties without writing custom class methods. The table below lists the functions.

Property Type	Set Property	Get Property
Integer	<code>set_int_property(...)</code>	<code>get_int_property(...)</code>
Double	<code>set_double_property(...)</code>	<code>get_double_property(...)</code>
Bool	<code>set_bool_property(...)</code>	<code>get_bool_property(...)</code>
String	<code>set_string_property(...)</code>	<code>get_string_property(...)</code>

Example code for GNU Radio Companion YAML Block Description file

```
templates:
  imports: |-
    import example
  make: |-
    example.gain(
      self.rfnoc_graph,
      uhd.device_addr(${block_args}),
      ${device_select},
      ${instance_select})
    self.${id}.set_int_property('gain', ${gain})
  callbacks:
    - set_int_property('gain', ${gain})
```